

Chapter 6: Synchronization

CS 3423 Operating Systems
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Overview

- Background
- Critical Section
- Synchronization
- Semaphores
- Classical Problem of Synchronization
- Monitors

Background

- Concurrent access to shared data
 - => possible data inconsistency
- Solution
 - mechanisms to ensure orderly execution of cooperating processes

Consumer-Producer Problem

- use count in addition to in, out

// Producer

```
while (1) {  
    nextItem = getItem();  
    while(count==BUFSIZE) ;  
    buffer[in] = nextItem;  
    in = (in+1) % BUFSIZE;  
    count++;  
}
```

// Consumer

```
while (1) {  
    while(count==0) ;  
    item =buffer[out];  
    out = (out+1) % BUFSIZE;  
    count--;  
}
```

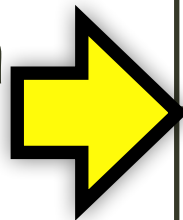
- problem: count++ and count--
implementation in machine language

Incr/decr operation

- depending on the instruction set
 - increment (or decr.) may take multiple instructions
- CISC: one instruction
 - `INC R1` or `INC MEM` ;; VAX/PDP11 -- (this is how C got ++)
 - `INC R0` or `INC A` ;; 8051 increment
- Most other architectures (RISC): multiple instructions!
 - `LA $4, mem` ;; this is actually `LUI` followed by `ORI` on MIPS
 - `LW $10, ($4)` ;; load data from address is in reg \$4 to reg \$10
 - `ADDI $10, $10, 1` ;; perform the addition in register \$10
 - `SW $10, ($4)` ;; write result back to same location (\$4)

Context Switching (ideal)

context
switch
here



Producer	Consumer	Prod. \$10	Cons. \$10	shared count
LA \$4, mem		-	-	5
LW \$10, (\$4)		5		6
ADDI \$10, \$10, 1		6		
SW \$10, (\$4)				6
	LA \$4, mem	6	-	6
	LW \$10, (\$4)		6	5
	SUBI \$10, \$10, 1		5	
	SW \$10, (\$4)			5

Context Switching (race: stale count overwriting consumer)

	Producer	Consumer	Prod.'s \$10	Cons.'s \$10	shared count
	LA \$4, mem		-		5
	LW \$10, (\$4)		5	-	
	ADDI \$10, \$10, 1		6		
context switch here (#1)		LA \$4, mem	6	-	
		LW \$10, (\$4)		5	
		SUBI \$10, \$10, 1		4	
		SW \$10, (\$4)			4
and here (#2)	SW \$10, (\$4)		6	4	6

- before switching back (#2), the count value of 4 is incorrect
 - producer incremented already (count should be 6)
 - the decremented result should be 5, not 4.
- after context switch (#2), the count value of 6 is incorrect,
 - producer's value was 6 but now after consumer, it should be 5.

Race Condition

- Inconsistent computation results from concurrent execution
 - final result depends on which process finishes last
- Solutions for Uniprocessor
 - **disable interrupt** => disables context switching
 - **nonpreemptive** (cooperative) CPU scheduling
- General Solution
 - synchronization among concurrent processes
 - mechanisms for "**critical section**"

Critical Section

The Critical-Section Problem

- Wanted: a protocol for processes to access shared data structure
- Problem statement
 - Processes $P_0..P_{n-1}$ competing for accessing shared data
 - **Critical section:**
 - Code segment that accesses shared data w/ mutual exclusion
 - **Mutual exclusion** property:
 - when one process is executing in its critical section, no other process is allowed to execute its critical section

Critical-Section Problem

- General code structure of typical process
 - at most one process can be in critical section at a time
 - **do** {
 section entry
 critical section
 section exit
 remainder section
} **while** (1);

3 Requirements of Critical Section

1. **Mutual Exclusion** (at most one process in CS at a time)
 - one process in CS $\Rightarrow$ no other processes in CS
2. **Progress**
 - if no process in CS, and some processes wish to enter CS $\Rightarrow$ they must not be blocked indefinitely.
3. **Bounded Waiting** (bound on wait time, not just finite)
 - A bound must exist on the number of times that other processes are allowed to enter their CS after a process has made a request to enter its CS
- Q: How to design **entry** and **exit** sections to satisfy the above requirements?

Critical Section Solution and Synchronization Tools

- Software solution
- Synchronization hardware
- Semaphore
- Monitor

Software Solution

- Nonpreemptive
 - easy - no race condition!
(assumption: no process (or thread) yields in the middle of a critical section)
 - but no CPU protection (a process can hog CPU)
- Preemptive
 - Peterson's for two processes

Peterson's for Two Processes

- Shared variables between Processes P_0 and P_1
 - **int** turn = 0; *// 0 or 1 to indicate P_0 or P_1 's turn*
 - **boolean** flag[2] = { FALSE, FALSE }; *// flag[i] true if P_i ready to enter CS*
- **if** (flag[j] == FALSE or turn == i), **then** P_i can enter its critical section

```
flag[0] = TRUE;
turn = 1;
while (flag[1] && turn == 1) ;
critical section
remainder
flag[0] = FALSE;
```

P_0

```
flag[1] = TRUE;
turn = 0;
while (flag[0] && turn == 0);
critical section
remainder
flag[1] = FALSE;
```

P_1

assumption: no hardware support, can context switch anywhere!

Peterson's Solution for Two Processes

- Mutual exclusion [Yes]
 - when $\text{flag}[0] == \text{flag}[1] == \text{TRUE}$, rely on *turn* (which can be either 0 or 1) $\Rightarrow$ mutually exclusive
- Bounded wait [Yes]
 - after $\text{flag}[i]$ executes, always sets its own $\text{flag}[i] = \text{FALSE}$, and *turn* is already $== j$, so P_j can run
- Progress [Yes]
 - **while** loop's condition for i will always have an AND condition broken by j , if not already

Issues with Peterson's Solution

- Software only
 - does not require hardware support
- Not guaranteed to work on modern CPU
 - Compiler or CPU may reorder instructions if no dependencies
 - a CPU may have multiple hardware threads and thus see values not in code order
- Solution: use proper synchronization tools

Hardware Support for Synchronization

Hardware Support for Synchronization

- Memory barriers
 - an instruction to explicitly ensure memory is loaded in code order
- Hardware instructions
 - atomic instructions
- Atomic variables
 - variables whose updates are atomic

Hardware support for locking primitives

- Lock must be atomic
- Uniprocessor
 - simply disable interrupt in critical section
- Multiprocessor
 - disabling interrupt either infeasible or too inefficient
- Modern machines
 - atomic test-and-set
 - swap content of two words in memory

Atomic Test-and-Set

Executes
atomically

- ```
bool TestAndSet(bool &lock) {
 bool value = lock; // save old value
 lock = TRUE; // lock anyway, whether we got the lock
 return value; // we got lock if it was unlocked,
} // but if someone else got lock, return TRUE
```
- lock is a shared variable indicating locking state.
- At most one process at a time should get the lock
- Protocol
  - if currently unlocked, lock it as part of testing!  
(and you own the lock)
  - To unlock, the lock owner simply sets lock = FALSE;

# Example

- ```
do {  
    while (TestAndSet(lock)) ; // get lock  
    critical section;  
    lock = FALSE; // unlock  
} while (1);
```
- All processes do something like this
 - Locking by `while (TestAndSet(lock)) ;`
 - unlocking by simply `lock = FALSE;`
 - at most one process at a time will hold the lock

Atomic CompareAndSwap()

- Similar to, more general than atomic test-and-set
 - AtomicSwap(&lock, value)
 - value could encode the owner of lock
- Code (executed atomically)
 - `int CompareAndSwap(int *val, int expected, int newVal) {
 int temp = *val;
 if (*val == expected)
 *val = newVal;
 return temp;
}`

Atomic Variables

- primitive types and associated functions
 - e.g., increment, assign
 - often implemented w/ atomic compare-and-swap
- not the same as critical section
 - example: single producer, multi-consumer
 - both consumers wait for count > 0
 - if count became 1, both consumers could unblock
 - Applicability limited to single update of shared data, rather than being guards on other shared data structure

Mutex Locks

- Motivation:
 - Previous solutions are complicated, inaccessible to application programmers
 - Solution provided by OS designers for critical section
- Simplest is mutex lock
 - **acquire()** a lock before entering a critical section, **release()** the lock when exiting the critical section => both atomic
 - Boolean variable indicating whether lock is available
 - Usually implemented via hardware atomic instructions
- Problem
 - Requires busy waiting, called a *spinlock*

Example in Python

- `import threading`
- `L = threading.Lock() # constructor call.`
- `L.acquire()`
 - blocks until the lock L is acquired
- Can also do polling
 - `L.acquire(blocking=False)` => try acquiring lock L, return successful lock or not, but does not block in either case.
- `L.release()`
 - any thread can unlock L, not just the original thread that locks it!

Semaphores

Semaphore

- Originally, a way to encode symbols using two flags
- Real-time long-distance optical communication before the days of telecommunication
- But.. that's not what it means in CS

THE SEMAPHORE ALPHABET.

CHAR- ACTERS	HAND FLAGS	CHAR- ACTERS	HAND FLAGS	CHAR- ACTERS	HAND FLAGS	CHAR- ACTERS	HAND FLAGS
A		H		O		V	
B		I		P		W	
C		J		Q		X	
ANSWER- ING SIGN		K		R		Y	
D		L		S		Z	
E		M		T		ATTEN- TION	
F		N		U		BREAK	
G							

credit: <http://www.cs.dartmouth.edu/~rockmore/semaphore.html>

Semaphore - history

- Proposed by Dijkstra in 1962-1963
 - for THE multiprogramming system
 - purpose: very simple mechanism for supporting synchronization
- Two primitives (system calls) on an integer variable
 - **P**() => to probe ("proberen" in Dutch), test
 - **V**() => to increment ("verhogen" in Dutch)
- Modern OS terms
 - **P**() => `wait()`, **V**() => `signal()`

Semaphore - in computer science

- A variable S that contains an `int` for controlling access to shared resources
 - serves as a "count" # instances available or deficit
 - mutex is special case of semaphore where S is binary instead of `int`
- 2 primitives: `wait(S)` and `signal(S)`
 - must be paired up, either within the same thread or across different threads

Semaphore implementation:

Busy-wait version

- busy-wait implementation
 - assume `S` is `int`, also assume preemption to switch context
 - `wait(S):` // originally called `P()`
 `while (S <= 0) ;` // busy wait: no rsrc avail
 `S--;` // got unblocked, grab it by decr count
 - `signal(S):` // originally called `V()`
 `S++;` // give back 1 instance of rsrc to pool
- issues with busy wait version
 - inefficient, for same reason as polling
 - solution: use wait queue to allow another thread/process to run

Semaphore Usage

- Counting Semaphore (initialize $S = N > 1$)
 - N instances of resource, S initialized to N
- Binary Semaphore (initialize $S = 1$)
 - Number is binary (0 or 1) $\Rightarrow$ mutex
- Barrier (initialize $S = 0$)
 - for enforcing precedence (event A must precede event B)
- Implementation
 - Busy-wait: simple but inefficient use of CPU cycles
 - Non-busy-wait: use a waiting queue

Real-life example for semaphore

- N parking spots
- Up to N cars can park without waiting
- if $> N$ cars, must wait for some car to leave
 - negative value = #cars waiting
 - 5 means 5 cars waiting. 0 means full & no waiting
- Question: policy for unblocking
 - wait in line (FIFO)?
 - whoever grabs it first (FCFS)?



Parking lot illustration

	time	0	1	2	3	4	5	6	7	8	9	10	11	12	13
car	0		arrv	park	p	p	dep								
	1			arrv	p	p	p	p	p	p	p	p	dep		
	2			arrv	p	p	p	p	dep						
	3			arrv	p	p	p	p	p	p	dep				
	4				arrv	p	p	p	p	p	p	p	p	p	p
	5				arrv	wait	w	park	p	p	p	p	p	p	p
	6				arrv	wait	w	w	w	park	p	p	p	dep	
	7					arrv	wait	w	w	w	w	park	p	p	p
	8														arrv
value		5	4	1	-2	-3	-2	-2	-1	-1	0	0	1	2	1
spot	0	-	car0	0	0	0	-	car5	5	5	5	5	5	5	5
	1	-	-	car1	1	1	1	1	1	1	1	1	-	-	car8
	2	-	-	car2	2	2	2	2	-	car6	6	6	6	-	-
	3	-	-	car3	3	3	3	3	3	3	-	car7	7	7	7
	4	-	-	-	car4	4	4	4	4	4	4	4	4	4	4

Barrier: forcing ordering between concurrent processes

- Example
 - P_1 executes S_1 , and P_2 executes S_2
 - Both P_1 and P_2 require S_1 to precede S_2
- Semaphore implementation

semaphore sync = 0;

// in P_1 :

S_1 ;

signal(sync);

// in P_2 :

wait(sync);

S_2 ;

Example: more general sync in a DAG

(Initially, all semaphores are 0)
begin

P₁: S₁; signal(a); signal(b);

P₂: wait(a); S₂; signal(c);

P₃: wait(b); S₃; signal(d);

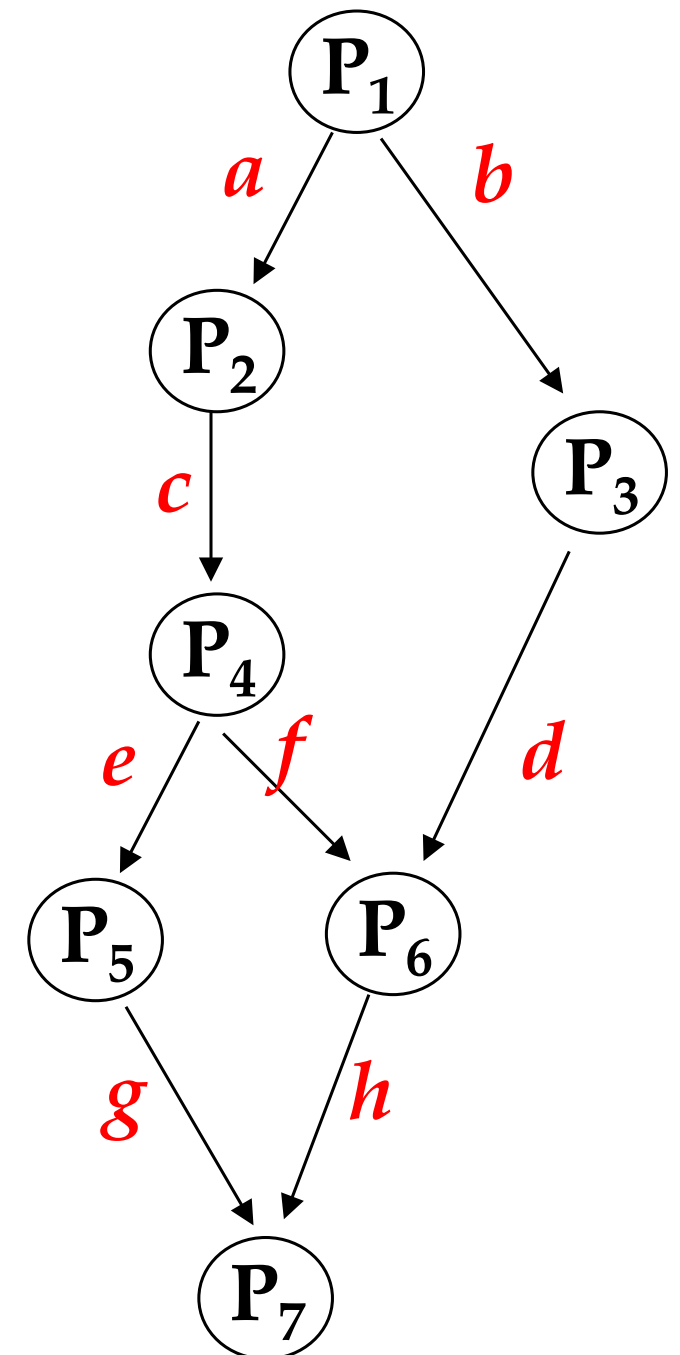
P₄: wait(c); S₄; signal(e); signal(f);

P₅: wait(e); S₅; signal(g);

P₆: wait(f); wait(d); S₆; signal(h);

P₇: wait(g); wait(h); S₇;

end



i.e., each edge x corresponds to signal(x) to wait(x)

n-process Critical Section

- shared data:
 - semaphore mutex;
- Process P_i :
 - **do** {
 wait(mutex); // e.g., pthread_mutex_lock()
 critical section
 signal(mutex); // e.g. pthread_mutex_unlock()
 remainder section
} **while** (1);
- Progress? Yes.
- Bounded wait? Depends on implementation of wait()

Semaphores without busy wait

C struct looks like this:
container of int and linked list

```
typedef struct {  
    int value;  
    struct PCB *waitlist;  
} semaphore;
```

pseudo
code in
python
syntax

```
def wait(S):  
    S.value -= 1 // deduct #avail rsrc instances  
    if (S.value < 0):  
        // not enough rsrc to proceed, we wait in line  
        S.waitlist.append(thisProcess)  
        sleep; // switch context to someone else  
        // else no blocking!
```

```
def signal(S):  
    S.value += 1 // give back #avail rsrc instances  
    if (S.value <= 0):  
        P = S.waitlist.dequeue() // could be priority  
        wakeup(P) // put P back in ready queue  
        // else there is nobody to unblock
```

Semaphores without busy wait

- Process linked list
 - may use any queuing policy: FIFO, LIFO, etc, or some kind of priority queue
- Assume available system calls
 - adding process itself to waitlist and **sleep** (like **yield**) => won't get waken till another `signal()` calls `wakeup` on us
 - **wakeup(*P*)**: wake up a process *P* by moving it from waitlist back into ready queue
 - Q: how to select *P* to wake up?
A: depends on policy

Busy Wait or Not?

- Depends on length of critical section
- Short (a few instructions) => busy wait
 - easier, rarely occupied, finishes quickly
 - lower overhead esp. for multiprocessor
- Long (minutes, hours) => non-busy-wait
 - busy waiting too inefficient!
 - better to go on wait queue, worth multiprocessor overhead

Issue with Semaphores

- too low level
 - wait() and signal() are two separate calls
 - wait first, then signal; barrier may do in either order
 - must be matched up or else in trouble
 - programmer must be sure!
- Nobody reinforces pairing or ordering...
 - what if code calls signal() then wait() or without wait() ? e.g., on mutex => breaks critical section!
 - what if code calls wait() without signal()? => hogs resources!

Monitors

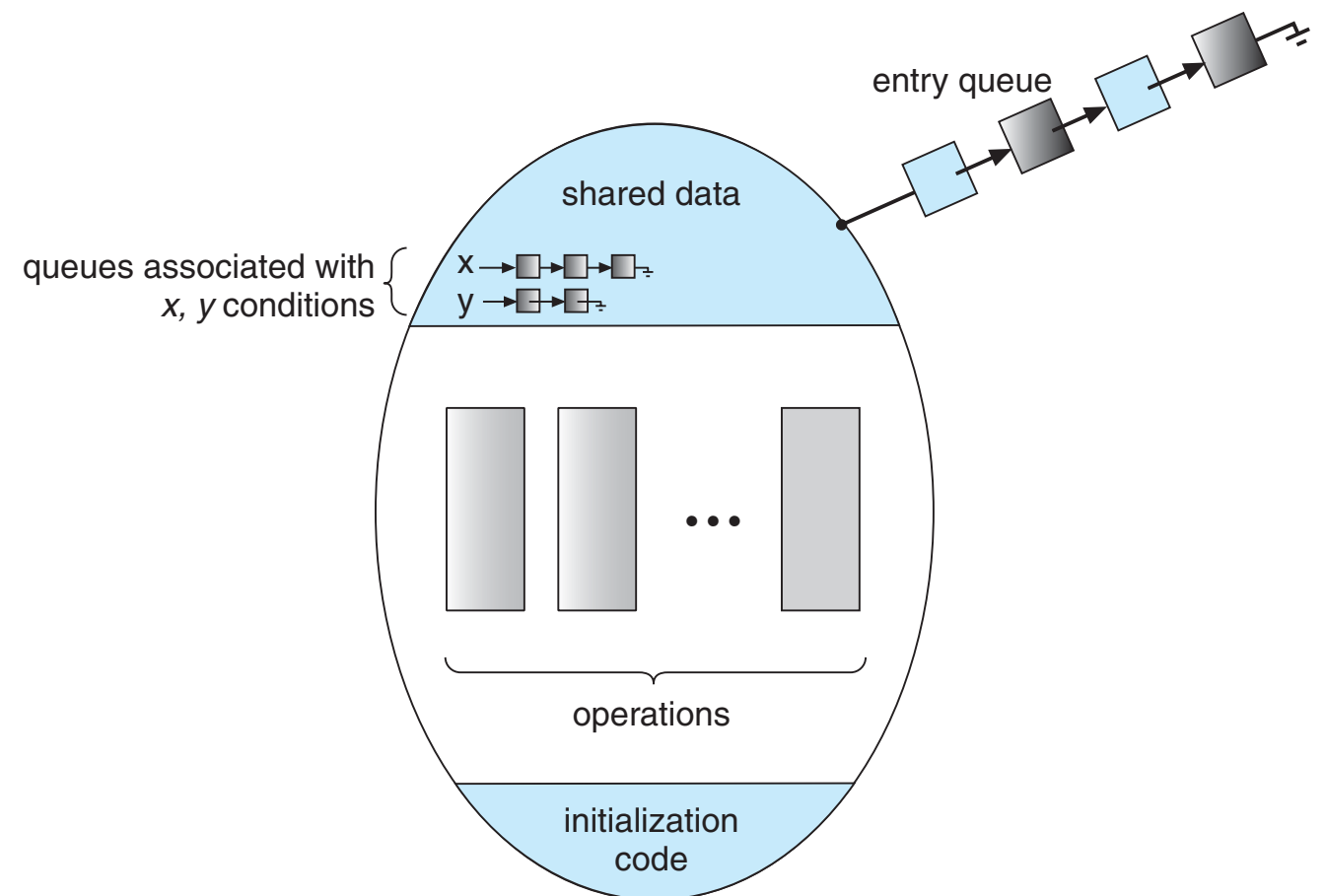
Monitor

- A "synchronized object"
 - think: object-oriented programming
- Instance of abstract data type (ADT="class")
 - **encapsulates** shared data
 - provides **methods** to access resources
 - methods invocations by multiple processes or threads are serialized
- Languages that support monitor concepts
 - concurrent Pascal, C#, Java, Python, ..
- Methods synchronize by **condition variables**

Monitor declaration with condition variables

```
monitor MonitorName:  
    # shared variable declaration  
  
    def method1(...):  
        # synchronized access  
  
    def method2(...):  
        # synchronized access  
  
    def __init__(...):  
        # initialize
```

- condition variables
- `x.wait()`, `x.signal()`

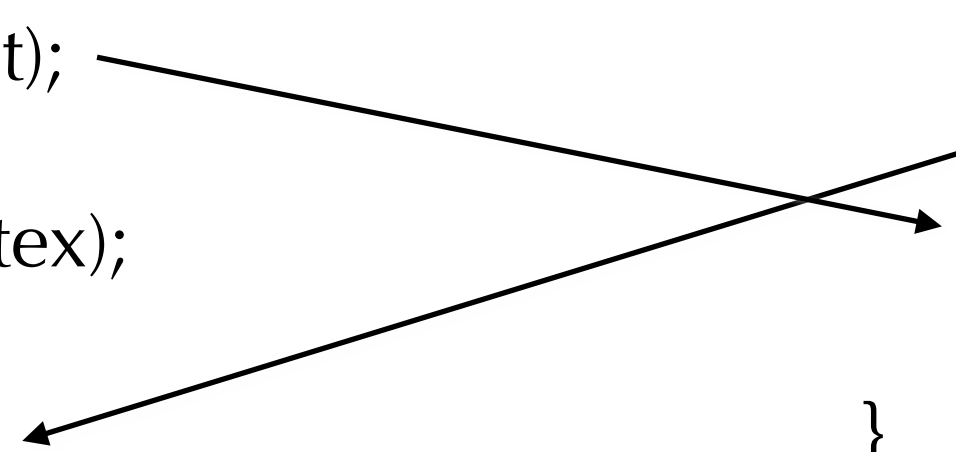


Monitor Implementation (1/2)

Using Semaphores

- Variables
 - semaphore mutex, */* (initially = 1) */* next; */* (initially = 0) */*
int next_count = 0;
- Each procedure F will be replaced by
 - wait(mutex);
body of F;
if (next_count > 0) {
 signal(next); *// barrier, tell next in dependency order to wake*
} *else* {
 signal(mutex); *// no more next count, now release mutex*
}
- Mutual exclusion within a monitor is ensured

Monitor Implementation (2/2) – Condition Variables

- For each **condition variable** x , we have:
 - semaphore x_sem ; // (initially = 0), also barrier
`int` $x_count = 0$;
 - **$x.wait()$**
 - $x_count++$;
`if` ($next_count > 0$) {
 `signal(next)`;
} `else` {
 `signal(mutex)`;
}
`wait(x\_sem)`;
 $x_count--$;
 - **$x.signal()$**
 - `if` ($x_count > 0$) {
 $next_count++$;
 `signal(x\_sem)`;
 `wait(next)`;
 $next_count--$;
}
- 

Resuming Processes within a Monitor

- If several processes queued on condition `x`, and `x.signal()` executed, which should be resumed?
- FCFS frequently not adequate
- Priority scheme may be more suitable
 - conditional-wait construct in the form of `x.wait(c)`, where `c` is priority number
 - Process with lowest number (highest priority) is scheduled next

Issue with Monitors

- access permission
 - assumed, but how to be sure?
- a process might ...
 - never release a resource
 - release a resource it never requested - by mistake
 - request same resource multiple times (without releasing first)