

## Singular Value Decomposition (SVD)

$$A_{m \times n} = U \Sigma V^T$$

$$(A^T A) \underline{v}_i = \lambda_i \underline{v}_i, \quad \lambda_1 \cdots \lambda_r > 0, \quad \lambda_{r+1} = \cdots = \lambda_n = 0, \quad \underline{u}_i = \frac{A \underline{v}_i}{\sigma_i}, \quad \sigma_i = \sqrt{\lambda_i} > 0$$

Remark 1 半正定 symmetric matrix  $A = Q \Lambda Q^T$

$$\text{Remark 2 } \begin{matrix} m \times n \\ n \times m \end{matrix} A A^T = (U \Sigma V^T)(V \Sigma^T U^T) = U \Lambda U^T \Rightarrow (A A^T) \underline{u}_i = \lambda_i \underline{u}_i$$

- o  $\begin{cases} (A^T A) \underline{v}_i = \lambda_i \underline{v}_i & \text{for } i = 1 \dots n \\ (A A^T) \underline{u}_i = \lambda_i \underline{u}_i & \text{for } i = 1 \dots m \end{cases}$

Therefore,  $\underline{u}_1 \dots \underline{u}_m$  are orthogonal eigenvectors of  $A A^T$  with corresponding eigenvalues  $\lambda_1 \dots \lambda_r, 0 \dots 0$

Recall that  $\underline{v}_1 \dots \underline{v}_n$  are orthogonal eigenvectors of  $A^T A$  with corresponding eigenvalues  $\lambda_1 \dots \lambda_r, 0 \dots 0$

$$\text{Remark 3 } A^T (A \underline{v}_i) = \lambda_i \underline{v}_i \quad \lambda_i > 0 \text{ for } i = 1 \dots r \quad \therefore$$

$\underline{v}_1 \dots \underline{v}_r$  form an orthonormal basis for  $C(A^T)$

$\underline{v}_{r+1} \dots \underline{v}_n$  form an orthonormal basis for  $N(A)$

[  $C(A^T), N(A)$  is orthogonal complement ]  $\mathbb{R}^n$

$$A \underline{v}_i = \sigma_i \underline{u}_i \text{ for } i = 1 \dots r \quad \therefore$$

$\underline{u}_1 \dots \underline{u}_r$  form an orthonormal basis for  $C(A)$

$\underline{u}_{r+1} \dots \underline{u}_m$  form an orthonormal basis for  $N(A^T)$

[  $C(A), N(A^T)$  is orthogonal complement ]  $\mathbb{R}^m$

## Applications of SVD

$$A = U \Sigma V^T = \underline{u}_1 \sigma_1 \underline{v}_1^T + \dots + \underline{u}_r \sigma_r \underline{v}_r^T \quad \text{Suppose } \sigma_1 \geq \sigma_2 \dots \geq \sigma_r > 0$$

(1) 用於影像壓縮 to approximate  $A$ , 只保留足夠大  $\sigma_i$  項的和

(2) In multiple-input multiple-output (MIMO) transmission, the channel  $H = U \Sigma V^T$

where the MIMO channel is decomposed into  $r$  uncoupled parallel subchannels with  $\sigma_i$  as the amplitude channel gain of the  $i$ th parallel subchannel.

\* Operator Norm or Norm of a matrix  $A$ :  $\|A\| = \sigma_{\max}$

\* Frobenius Norm of a matrix  $A$ :  $\|A\|_F = \sqrt{\sigma_1^2 + \dots + \sigma_r^2} = \sqrt{\sum |a_{ij}|^2}, A = [a_{ij}]$

## Linear transformations

Def A transformation  $T$  from a vector space  $V$  to a vector space  $W$  assigns to each input vector  $\underline{v} \in V$  an output  $T(\underline{v})$  in  $W$ . We write  $T: V \rightarrow W$



Def A transformation  $T$  is linear if all  $\underline{v}$  and  $\underline{w}$

$$(i) \quad T(\underline{v} + \underline{w}) = T(\underline{v}) + T(\underline{w})$$

$$(ii) \quad T(c\underline{v}) = cT(\underline{v}) \quad \forall c$$

Remark 1  $T(\underline{0}) = \underline{0}$  if  $T$  is linear  $T(\underline{0}) = T(\underline{0} + \underline{0}) = T(\underline{0}) + T(\underline{0}) = 2T(\underline{0})$

Remark 2 (i). (ii)  $\Rightarrow T(c\underline{v} + d\underline{w}) = cT(\underline{v}) + dT(\underline{w}) \quad \forall c, d, \underline{v}, \underline{w}$

Remark 3  $T(c_1\underline{v}_1 + \dots + c_n\underline{v}_n) = \sum_i^n c_i T(\underline{v}_i)$  if  $T$  is linear

Remark 4 If  $V = W$ , then a linear transformation

$T: V \rightarrow V$  is called a linear operator on  $V$

Def Range of  $T \triangleq \{T(\underline{v}): \underline{v} \in V\}$  ex:  $C(A)$

Def Kernel of  $T \triangleq \{\underline{v}: T(\underline{v}) = \underline{0}\}$  ex:  $N(A)$

Remark The range of  $T$  is a subspace of  $W$ , the kernel of  $T$  is a subspace of  $V$

## Matrix Representation of a Linear transformation

Suppose  $\beta = \{\underline{v}_1 \dots \underline{v}_n\}$  is a basis of  $V$  and  $\gamma = \{\underline{w}_1 \dots \underline{w}_m\}$  is a basis of  $W$

For every  $\underline{v} \in V$ , we have  $\underline{v} = x_1\underline{v}_1 + \dots + x_n\underline{v}_n$ .

Since  $T(\underline{v}) \in W$ , we can have  $T(\underline{v}) = y_1\underline{w}_1 + \dots + y_m\underline{w}_m$ .

$$\text{Let } \underline{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \quad \text{and } \underline{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$$

(coordinates of  $\underline{v}$  with respect to  $\beta$ ) (coordinates of  $T(\underline{v})$  with respect to  $\gamma$ )

Since  $T(\underline{v}_j) \in W$  for  $j = 1 \dots n$

$$\text{we can have } T(\underline{v}_j) = a_{1j}\underline{w}_1 + \dots + a_{mj}\underline{w}_m = \sum_{i=1}^m a_{ij}\underline{w}_i$$

$$\begin{aligned}
 \text{Then } T(\underline{v}) &= T(x_1 \underline{v}_1 + \cdots + x_n \underline{v}_n) = T\left(\sum_{j=1}^n x_j \underline{v}_j\right) = \sum_{j=1}^n x_j T(\underline{v}_j) = \sum_{j=1}^n x_j \sum_{i=1}^m a_{ij} \underline{w}_i \\
 &= \sum_{j=1}^n \sum_{i=1}^m a_{ij} x_j \underline{w}_i = \sum_{i=1}^m \left( \sum_{j=1}^n a_{ij} x_j \right) \underline{w}_i = \sum_{i=1}^m y_i \underline{w}_i \quad \therefore y_i = \sum_{j=1}^n a_{ij} x_j \text{ for } i = 1 \dots m \\
 \Rightarrow \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix} &= \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \Rightarrow \underline{y} = A \underline{x} .
 \end{aligned}$$

We write  $[T]_{\beta(m)}^{\gamma(m)} = A_{(m \times n)}$  If  $\beta = \gamma$ , we write  $[T]_{\beta} = A$