

Similar Matrices

Recall $A = S^{-1}AS$

Def Let M be any 可逆矩陣. Then $B = M^{-1}AM$ is similar to A

Remark 1 The process from A to B is called similarity transformation

Remark 2 A is similar $A = I^{-1}AI$ (reflexivity)

Remark 3 A, B 相互 similar $B = M^{-1}AM \Rightarrow A = (M^{-1})^{-1}B(M^{-1})$ (symmetry)

Remark 4 If A, B similar and B, C similar, then A, C similar $B = M_1^{-1}AM_1, C = M_2^{-1}BM_2$
 $\Rightarrow C = M_2^{-1}(M_1^{-1}AM_1)M_2 = (M_1M_2)^{-1}A(M_1M_2)$ (transitivity)

Claim Similar matrices have the same eigenvalues

pf: Assume $B = M^{-1}AM \Rightarrow A = MBM^{-1}$

Suppose $A\underline{x} = \lambda\underline{x}$, then $MBM^{-1}\underline{x} = \lambda\underline{x} \Rightarrow B(M^{-1}\underline{x}) = \lambda(M^{-1}\underline{x})$

$B\underline{x}' = \lambda\underline{x}', \underline{x}' = M^{-1}\underline{x} \Rightarrow B$ 的 eigenvalue: λ eigenvector: $M^{-1}\underline{x}$

alternative pf: $\det(B - \lambda I) = \det(M^{-1}AM - \lambda I) = \det(M^{-1}(A - \lambda I)M)$

$= \det(M^{-1}) \det(A - \lambda I) \det(M) = \det(A - \lambda I) \Rightarrow A, B$ 有相同特徵多項式

\Rightarrow Have the same eigenvalues

Remark If \underline{x} is an eigenvector of A , then $M^{-1}\underline{x}$ is an eigenvector of $B = M^{-1}AM$

◦ All 2×2 matrices with eigenvalues $1, 0$ are similar to each other (This is generally true for matrices with all distinct eigenvalues)

◦ Same for A and $B = M^{-1}AM$

1. λ_i

2. Trace and 行列式

3. Rank

4. # of independent eigenvectors

5. Jordan form

3pf: Suppose $A\underline{x} = \underline{0}$, then $MBM^{-1}\underline{x} = \underline{0} \Rightarrow B(M^{-1}\underline{x}) = \underline{0}$. If $\underline{x} \in N(A)$, then $M^{-1}\underline{x} \in N(B)$

Conversely, if $\underline{x}' \in N(B)$, then $M\underline{x}' \in N(A)$. $c_1\underline{x}_1 + \dots + c_k\underline{x}_k = \underline{0} \Leftrightarrow$

$c_1(M^{-1}\underline{x}_1) + \dots + c_k(M^{-1}\underline{x}_k) = \underline{0}$ i.e. $\underline{x}_1, \dots, \underline{x}_k$ are L.I. $\Leftrightarrow M^{-1}\underline{x}_1, \dots, M^{-1}\underline{x}_k$ are L.I.

$\dim(N(A)) = \dim(N(B)) \Leftrightarrow \text{rank}(A) = \text{rank}(B)$

4pf: \underline{x} is an eigenvector of $A \Leftrightarrow M^{-1}\underline{x}$ is an eigenvector of B

5pf: Jordan form

If A has s independent eigenvectors, it is similar to a matrix J that has s

Jordan blocks on its diagonal.

Jordan form

$M^{-1}AM = \begin{bmatrix} J_1 & & 0 \\ & \ddots & \\ 0 & & J_s \end{bmatrix}$ each blocks in J has one eigenvalue λ_i , one eigenvector

and 1's above the diagonal. Jordan block: $J_i = \begin{bmatrix} \lambda_i & & 0 \\ & \lambda_i & \\ & & \ddots \\ 0 & & & \lambda_i \end{bmatrix}$

Remark 1 A is similar to B iff they share the same Jordan form

Remark 2 If A is diagonalizable, then $J = \Lambda$, the diagonal matrix with λ_i on the diagonal

Singular Value Decomposition (SVD)

Given $A^{m \times n}$, assume $\text{rank}(A) = r$. Since $A^T A$ is $n \times n$ and symmetric,

it has a complete set of n orthonormal eigenvectors, $A^T A \underline{v}_i = \lambda_i \underline{v}_i$ for $i = 1, \dots, n$

and each $\lambda_i \in \mathbb{R}$. We can have $\|A \underline{v}_i\|^2 = \underline{v}_i^T A^T A \underline{v}_i = \underline{v}_i^T \lambda_i \underline{v}_i = \lambda_i \|\underline{v}_i\|^2 = \lambda_i \geq 0$

Recall that $\text{rank}(A^T A) = \text{rank}(A) = r$ and # of nonzero eigenvalues of A equals

of nonzero pivots. There should be r nonzero eigenvalues of $A^T A$.

Assume $\lambda_1, \dots, \lambda_r > 0$ and $\lambda_{r+1} = \dots = \lambda_n = 0$. Let $\sigma_i = \sqrt{\lambda_i}$ for $i = 1, \dots, r$

These values are called singular values. Let $\underline{u}_i = \frac{A \underline{v}_i}{\sigma_i}$ for $i = 1, \dots, r$

$\|\underline{u}_i\|^2 = \frac{\|A \underline{v}_i\|^2}{\lambda_i} = \frac{\lambda_i}{\lambda_i} = 1$ and $\underline{u}_i^T \underline{u}_j = \frac{\underline{v}_i^T (A^T A \underline{v}_j)}{\sigma_i \sigma_j} = \frac{\lambda_j \underline{v}_i^T \underline{v}_j}{\sigma_i \sigma_j} = 0$ if $i \neq j$

Therefore, $\underline{u}_1, \dots, \underline{u}_r$ are orthonormal. By the Gram-Schmidt process, we can extend them

to a complete orthonormal basis for \mathbb{R}^m : $\underline{u}_1, \dots, \underline{u}_r, \underline{u}_{r+1}, \dots, \underline{u}_m$

$$\text{Then } A \underline{v}_i = \sigma_i \underline{u}_i \text{ for } i = 1, \dots, r \Rightarrow A \begin{bmatrix} \underline{v}_1 & \dots & \underline{v}_r \end{bmatrix} = \begin{bmatrix} \underline{u}_1 & \dots & \underline{u}_r \end{bmatrix} \begin{bmatrix} \sigma_1 & & \\ & \dots & \\ & & \sigma_r \end{bmatrix}$$

$$\Rightarrow A \begin{bmatrix} \underline{v}_1 & \dots & \underline{v}_n \end{bmatrix} = \begin{bmatrix} \underline{u}_1 & \dots & \underline{u}_m \end{bmatrix} \begin{bmatrix} \sigma_1 & \dots & \sigma_r & | & 0 \\ \hline 0 & & & | & 0 \end{bmatrix} \Rightarrow AV = U\Sigma \Rightarrow A = U\Sigma V^T$$

$$= \underline{u}_1 \sigma_1 \underline{v}_1^T + \dots + \underline{u}_r \sigma_r \underline{v}_r^T \text{ where } V^T = V^{-1} \text{ and } U^T = U^{-1}$$

This is called "Singular Value Decomposition (SVD)"