

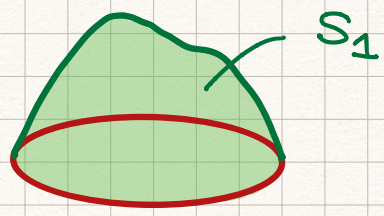
Stokes' Theorem

Recall the definition of curl,

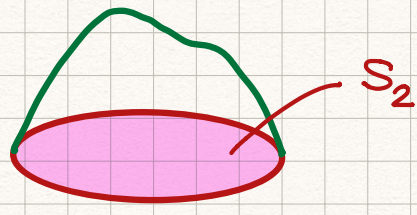
$$\vec{\nabla} \times \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_x & V_y & V_z \end{vmatrix} = (\partial_y V_z - \partial_z V_y, \partial_z V_x - \partial_x V_z, \partial_x V_y - \partial_y V_x)$$

Stokes' theorem

$$\oint_{\partial S} \vec{V} \cdot d\vec{r} = \int_S \vec{\nabla} \times \vec{V} \cdot d\vec{a}$$

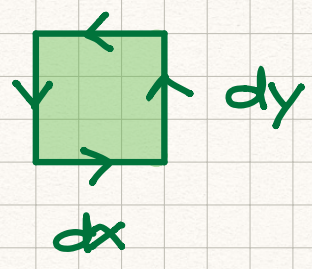


① $S_1 \neq S_2$ but $\partial S_1 = \partial S_2$,
Stokes' theorem still works



① Stokes' theorem doesn't
work for 1-side surface
(like Möbius strip)

Let's prove the theorem by Ms Loop on the
x-y plane :



circulation = $\oint_{\partial S} \vec{V} \cdot d\vec{r}$
 $= [V_x(y) - V_x(y+dy)] dx$
 $+ [V_y(x+dx) - V_y(x)] dy$

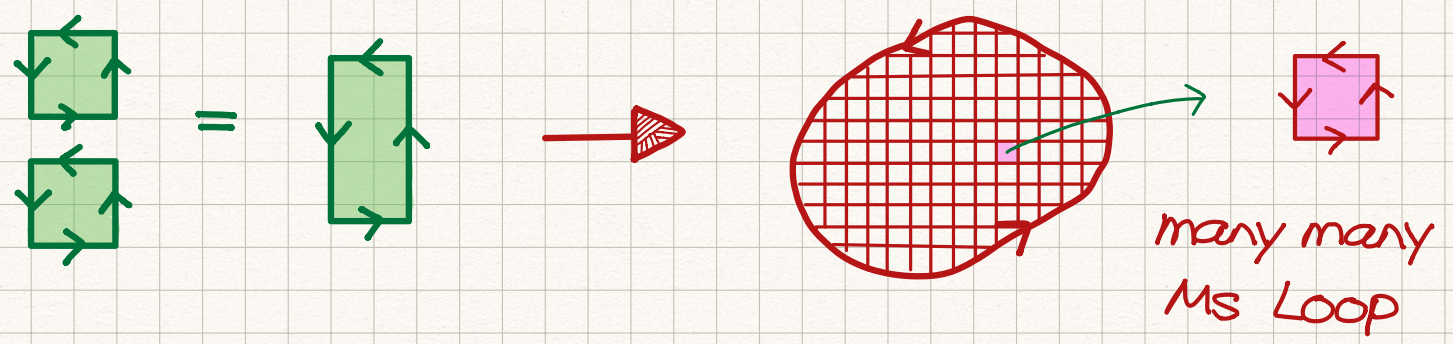
$$\oint_{\partial S} \vec{v} \cdot d\vec{r} = -\frac{\partial v_x}{\partial y} dy dx + \frac{\partial v_y}{\partial x} dx dy$$

$$= \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) dx dy$$

$$\int_S \vec{\nabla} \times \vec{v} \cdot d\vec{a} = (\vec{\nabla} \times \vec{v}) \cdot \hat{k} dx dy$$

$$= \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) dx dy$$

Thus, the circulation can also be computed by the surface integral of the curl.



So, the Stokes' theorem works for arbitrary closed contours on the x-y plane :

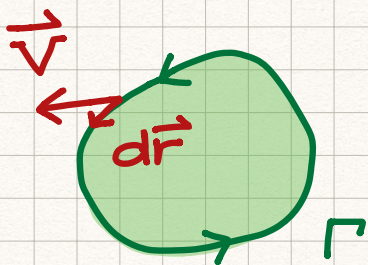
$$\oint_{\partial S} \vec{v} \cdot d\vec{r} = \int_S \vec{\nabla} \times \vec{v} \cdot d\vec{a}$$

The above results can be generalized to the 3D case (not a trivial task). 🤪

Conservative Field

Consider an irrotational vector field \vec{V} :

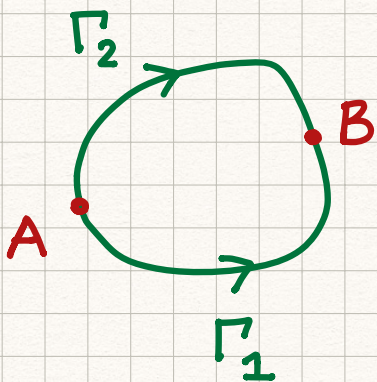
$$\vec{\nabla} \times \vec{V} = 0 \rightarrow \int_S \vec{\nabla} \times \vec{V} \cdot d\vec{a} = 0$$



According to the Stokes' thm,

$$\oint_{\partial S} \vec{V} \cdot d\vec{r} = 0$$

It's quite interesting that circulation along any closed contour is **ZERO**!

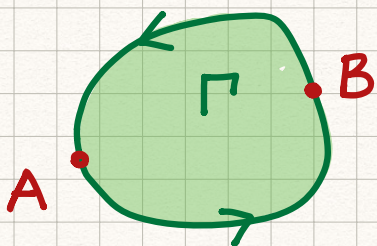


Consider two line integrals

$$I_1 = \int_{\Gamma_1} \vec{V} \cdot d\vec{r}$$

$$I_2 = \int_{\Gamma_2} \vec{V} \cdot d\vec{r}$$

Reversing Γ_2 to combine Γ_1 into a closed contour Γ .



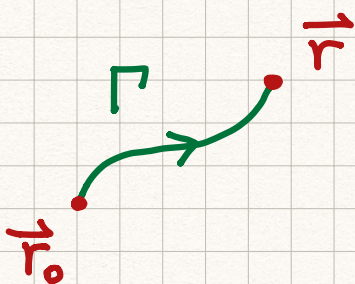
$$\underbrace{\oint_{\Gamma} \vec{V} \cdot d\vec{r}}_{\text{zero}} = \int_{\Gamma_1} \vec{V} \cdot d\vec{r} - \int_{\Gamma_2} \vec{V} \cdot d\vec{r}$$

$$\rightarrow \int_{\Gamma_1} \vec{V} \cdot d\vec{r} = \int_{\Gamma_2} \vec{V} \cdot d\vec{r} = \phi(\vec{r}_B) - \phi(\vec{r}_A)$$

The important conclusion here is ~

The notion of potential $\phi(\vec{r})$ works for an irrotational vector field $\vec{V}(\vec{r})$.

We may go further to derive the relation between ϕ and \vec{V} ☺



Because $\vec{\nabla} \times \vec{V} = 0$, the potential can be defined,

$$\phi(\vec{r}) = \phi(\vec{r}_0) + \int_{\Gamma} \vec{V} \cdot d\vec{r}$$

But, from the relation $d\phi = \vec{\nabla}\phi \cdot d\vec{r}$

$$\Delta\phi = \phi(\vec{r}) - \phi(\vec{r}_0) = \int_{\Gamma} \vec{\nabla}\phi \cdot d\vec{r}$$

$$\rightarrow \phi(\vec{r}) = \phi(\vec{r}_0) + \int_{\Gamma} \vec{\nabla}\phi \cdot d\vec{r}$$

Thus, $\int_{\Gamma} [\vec{V} - \vec{\nabla}\phi] \cdot d\vec{r} = 0$ — for arbitrary contour Γ !

It means that

$$\vec{V} = \vec{\nabla}\phi$$

(sometimes with a minus sign)

Example \vec{E} field of a point charge Q

$$\vec{E} = \frac{Q}{4\pi\epsilon_0} \frac{1}{r^2} \hat{r} = \frac{Q}{4\pi\epsilon_0} \left(\frac{x}{(x^2+y^2+z^2)^{3/2}}, \frac{y}{(x^2+y^2+z^2)^{3/2}}, \frac{z}{(x^2+y^2+z^2)^{3/2}} \right)$$

$$(\vec{\nabla} \times \vec{E})_z = \frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} = \frac{Q}{4\pi\epsilon_0} \left[y \cdot \left(-\frac{3}{2}\right) (x^2+y^2+z^2)^{-5/2} \cdot 2x - x \cdot \left(-\frac{3}{2}\right) (x^2+y^2+z^2)^{-5/2} \cdot 2y \right] = 0$$

One can also compute the other components,

$$\vec{\nabla} \times \vec{E} = 0 \rightarrow \text{potential } \phi(\vec{r}) \text{ exists!}$$

One can construct the Coulomb potential

$$\phi(\vec{r}) = \frac{Q}{4\pi\epsilon_0} \frac{1}{r} \quad \text{note that } \frac{\partial r}{\partial x} = \frac{\partial}{\partial x} \sqrt{x^2+y^2+z^2} = \frac{x}{r}$$

$$\nabla\phi = -\frac{Q}{4\pi\epsilon_0} \frac{1}{r^2} \left(\frac{\partial r}{\partial x}, \frac{\partial r}{\partial y}, \frac{\partial r}{\partial z} \right) = -\frac{Q}{4\pi\epsilon_0} \frac{1}{r^2} \hat{r} = -\vec{E}$$

$\rightarrow \vec{E} = -\vec{\nabla}\phi$ — This relation holds true for electrostatics.

NOTE. From Maxwell equation (Faraday's Law)

$$\vec{\nabla} \times \vec{E} = -\frac{\partial B}{\partial t} \xrightarrow{\text{static}} \vec{\nabla} \times \vec{E} = 0$$

irrotational!

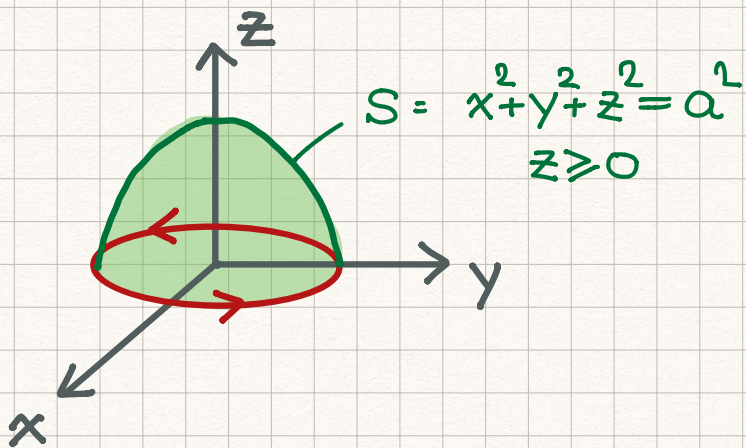
Thus, $\vec{E} = -\vec{\nabla}\phi$

In the presence of ~~AC~~ \rightarrow ,

$\vec{E} \neq -\vec{\nabla}\phi$... careful!

example

Circulation of the field



Given a vector field

$$\vec{V} = (4y, x, 2z),$$

want to compute

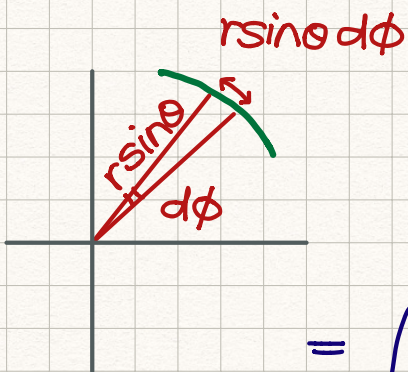
$$\int_S \nabla \times \vec{V} \cdot d\vec{a} = ?$$

There are 3 ways to go ☺

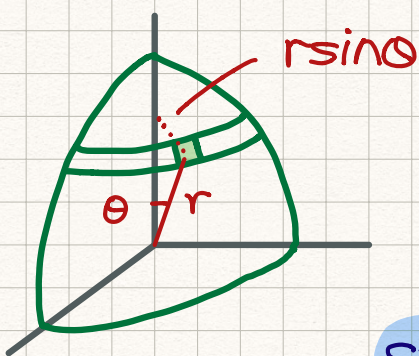
Method I. Directly evaluate the surface integral.

$$\nabla \times \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 4y & x & 2z \end{vmatrix} = (0, 0, -3) = -3\hat{k}$$

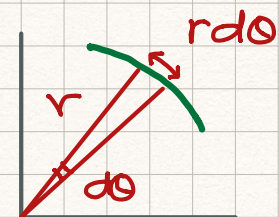
TOP view



$$d\vec{a} = r^2 \sin \theta d\theta d\phi \hat{n}$$



SIDE view



$$\int_S \nabla \times \vec{V} \cdot d\vec{a}$$

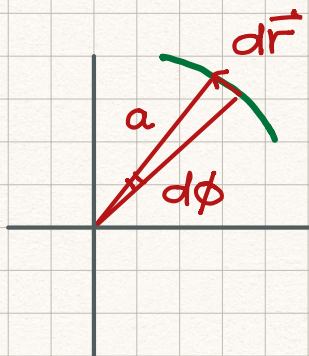
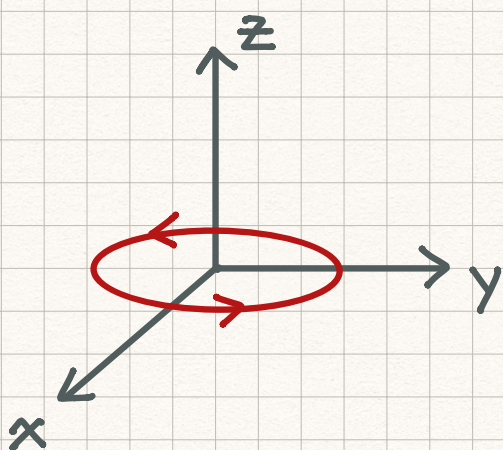
$$= \int_0^{2\pi} d\phi \int_0^{\pi/2} d\theta -3 \hat{k} \cdot \hat{n} r^2 \sin \theta$$

$$= \int_0^{2\pi} d\phi \int_0^{\pi/2} d\theta -3a^2 \sin \theta \cos \theta$$

$$= -\frac{3}{2} a^2 \cdot 2\pi \int_0^{\pi/2} d\theta \sin 2\theta$$

$$= -3\pi a^2$$

Method II. Make use of the Stokes' theorem.



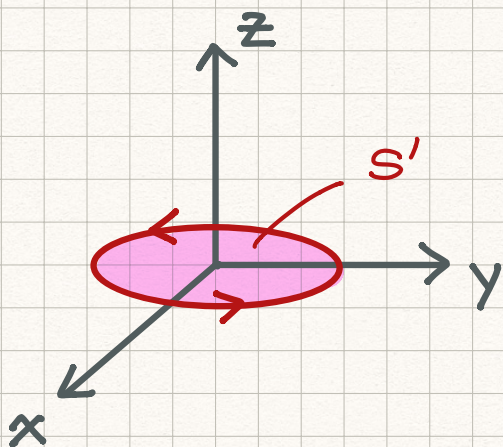
$$\begin{aligned} d\vec{r} &= dr \hat{e}_\phi \\ &= a d\phi \left(-\frac{y}{a}, \frac{x}{a}, 0 \right) \end{aligned}$$

$$\begin{aligned} \vec{\nabla} \cdot d\vec{r} &= (4y, x, 2z) \cdot (-y, x, 0) d\phi \\ &= (-4y^2 + x^2) d\phi \\ &= (-4\sin^2\phi + \cos^2\phi) a^2 d\phi \\ &= (1 - 5\sin^2\phi) a^2 d\phi \end{aligned}$$

$$\begin{aligned} \int_S \vec{\nabla} \times \vec{v} \cdot d\vec{a} &= \int_{\partial S} \vec{\nabla} \cdot d\vec{r} = \int_0^{2\pi} a^2 (1 - 5\sin^2\phi) d\phi \\ &= a^2 \cdot \left(1 - \frac{5}{2}\right) \cdot 2\pi = -3\pi a^2 \end{aligned}$$

the same result ☺

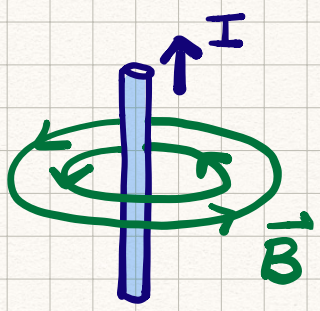
Method III. Choose another surface S'



$$\begin{aligned} \int_S \vec{\nabla} \times \vec{v} \cdot d\vec{a} &= \int_{S'} \vec{\nabla} \times \vec{v} \cdot d\vec{a} \\ &= \int_{S'} -3\hat{k} \cdot \hat{n} da \\ &= -3\pi a^2 \text{ — remarkable!} \end{aligned}$$



Vortex in the Field

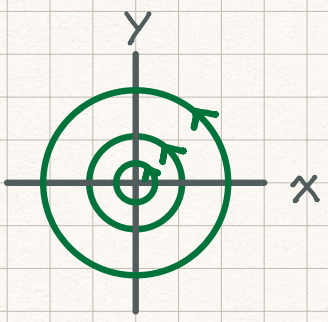


The magnetic field around an infinitely long wire is

$$\vec{B} = \frac{\mu_0 I}{2\pi\rho} \left(-\frac{y}{\rho}, \frac{x}{\rho}, 0 \right)$$

One can compute the curl:

$$\vec{\nabla} \times \vec{B} = 0 \text{ except @ the origin.}$$



Introduce the magnetic potential.

$$V_B = \frac{\mu_0 I}{2\pi} \phi = \frac{\mu_0 I}{2\pi} \tan^{-1}\left(\frac{y}{x}\right)$$

$$\vec{B} = \vec{\nabla} V_B = \left(\frac{\partial V_B}{\partial x}, \frac{\partial V_B}{\partial y}, \frac{\partial V_B}{\partial z} \right)$$

$$= \frac{\mu_0 I}{2\pi} \left(\frac{1}{1+(y/x)^2} \cdot -\frac{y}{x^2}, \frac{1}{1+(y/x)^2} \cdot \frac{1}{x}, 0 \right)$$

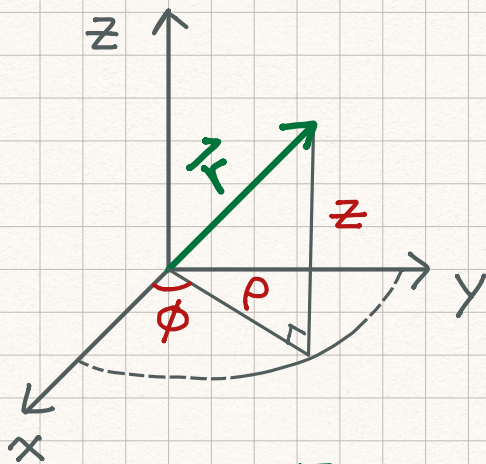
$$= \frac{\mu_0 I}{2\pi} \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2}, 0 \right) \text{ — Correct!}$$

Because the \vec{B} field can be expressed as $\vec{\nabla} V_B$,

$$\oint_{\Gamma} \vec{B} \cdot d\vec{r} = \oint_{\Gamma} \vec{\nabla} V_B \cdot d\vec{r} = 0 ?$$

From the Ampere's Law, $\oint_{\Gamma} \vec{B} \cdot d\vec{r} = \mu_0 I \neq 0$

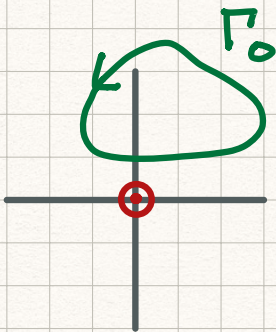
In cylindrical coordinates (ρ, ϕ, z)



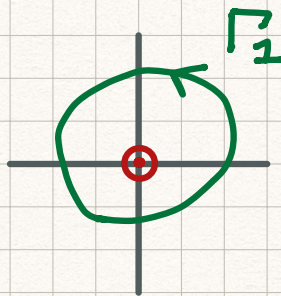
$$\vec{B} = \frac{\mu_0 I}{2\pi} \frac{1}{\rho} \hat{e}_\phi$$

and the potential is

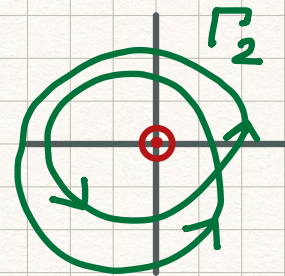
$$V_B = \frac{\mu_0 I}{2\pi} \cdot \phi$$



$$\Delta\phi = 0$$



$$\Delta\phi = 2\pi$$



$$\Delta\phi = 4\pi$$

$$\oint_{\Gamma} \vec{B} \cdot d\vec{r} = \mu_0 I \cdot W$$

W is the winding number of Γ .

NOTE. If one computes the curl carefully, the answer is not zero,

$$\vec{\nabla} \times \vec{B} = \mu_0 I \delta(x) \delta(y)$$

$$\text{So, } \oint_{\partial S} \vec{B} \cdot d\vec{r} = \int_S \vec{\nabla} \times \vec{B} \cdot d\vec{a} = \mu_0 I \ddot{}$$