#### Stationary Points 2

## The criterion to find the stationary points of a multi-variable in $f(x_1, x_2, \dots, x_N)$ is

df = 0

@ Without any constraint ~











Lagrange multiplier 1.

# $df = \vec{\nabla}f \cdot d\vec{r} \longrightarrow \vec{\nabla}f + \lambda \vec{\nabla}\phi = 0$

Not arbitrary 💬



#### Thermal Equilibrium

## When a system reaches thermal equilibrium,

З,

its entropy becomes maximum 00











 $e_{nP_{i}} = \lambda - 1$ ,  $P_{i} = e^{\lambda - i} = c_{onst}$ .



and the criterion for maximizing entropy is

P:= - microcanonical ensemble

#### And, the maximum entropy is

# $\sigma_{max} = -\pi e_n \pi \times n = -e_n \pi = e_n n$

## It can be shown that the thermal entropy S

## is related to Omax (not o in general)

S=KOmax=KCN

## For a system with thermal contact to reservoir,

 $\sum_{\alpha} P_{\alpha} = 1$ 

 $\sum_{\alpha} P_{\alpha} E_{\alpha} = U$ 

#### the constraints are different is

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T exchange energy

Pa

additional Constraint 4

#### Again, applying Lagrange multipliers to

#### find the maximum entropy "

# $\overset{*}{\sigma} = \sigma + \lambda_{1} \left( \sum_{\alpha} P_{\alpha} - 1 \right) + \lambda_{2} \left( \sum_{\alpha} P_{e} - U \right)$



# $e_{\Lambda}P_{i} = (\lambda_{i}-1) + \lambda_{2}E_{i} \longrightarrow P_{i} = e^{\lambda_{i}-1}e^{\lambda_{2}E_{i}}$

# Substitute into the constraint $\sum_{i=1}^{n} P_{i} = 1$ $P_{i} = \frac{\lambda_{2}E_{i}}{\sum_{i=1}^{n} e^{\lambda_{2}E_{i}}} = \frac{1}{2}e^{-E_{i}/kT}$

# ① It turns out $\lambda_2 = -\frac{1}{kT} \frac{v}{c}$ absolute temp $\frac{v}{c}$

## 2) $Z = \sum_{\alpha} e^{-E_{\alpha}/kT}$ is the partition fr.

## The probability distribution obtained in above

is the famous Boltzmann distribution:

# $P(E_i) = \frac{1}{Z_i} e^{-\frac{E_i}{kT}}$

The higher-energy states are exponentially

rare to find. This is the underlying reason

for scientific phenomena @ diff energy scales.



Riley, Hobson, Bence (3rd edition)







#### Thermodynamic Relations



10,

## Treating the internal energy U = U(S, V)

# $d\mathcal{U} = \left(\frac{\partial \mathcal{U}}{\partial s}\right)_{V} ds + \left(\frac{\partial \mathcal{U}}{\partial V}\right)_{S} dV$

#### By comparison, one can express T, P as





# The 2<sup>nd</sup> derivatives: $\frac{\partial \overline{U}}{\partial V \partial S} = \frac{\partial \overline{U}}{\partial S \partial V}$

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