Operating System: Chap12 Mass Storage System

National Tsing-Hua University 2016, Fall Semester

Overview

- **Disk Structure**
- Disk Scheduling
- Disk & Swap-Space Management
- **RAID**

Disk Structure

- Disk drives are addressed as large 1-dim arrays of logical blocks
	- logical block: smallest unit of transfer (**sector**)
- Logical blocks are mapped onto disk sequentially
	- ▶ Sector 0: 1st sector of 1st track on the outermost cyl.
	- \triangleright go from outermost cylinder to innermost one

Sectors per Track

Constant linear velocity (CLV)

- \triangleright density of bits per track is uniform
- \triangleright more sectors on a track in outer cylinders
- \triangleright keeping same data rate
	- \rightarrow increase rotation speed in inner cylinders
- applications: CD-ROM and DVD-ROM

■ **Constant angular velocity** (CAV)

- \triangleright keep same rotation speed
- \triangleright larger bit density on inner tracks
- \triangleright keep same data rate
- applications: hard disks

Disk IO

- Disk drive attached to a computer by an I/O bus EIDE, ATA, SATA (Serial ATA), USB, SCSI, etc \triangleright I/O bus is controlled by controller
	- **Host** controller (computer end)
	- **Disk** controller (built into disk drive)

Disk Scheduling

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Introduction

- Disk-access time has 3 major components
	- **seek time**: move disk arm to the desired **cylinder**
	- **rotational latency**: rotate disk head to the desired **sector**
	- **read time**: content **transfer time**
- Disk bandwidth:
	- \triangleright # of bytes transferred/(complete of last req start of first req)

Disk Scheduling

■ Minimize seek time

Seek time ≈ seek distance

■ Several algorithms exist to schedule the servicing of disk I/O requests **FCFS** (first-come, first-served) **SSTF** (shortest-seek-time-first) **SCAN C-SCAN** (circular SCAN) **LOOK and C-LOOK**

FCFS (First-Come-Frist-Served)

■ We illustrate them with a request queue (0-199) 98, 183, 37, 122, 14, 124, 65, 67

Head pointer 53

Illustration shows total head movement of 640 cylinders.

SSTF (Shortest-Seek-Time-First)

- SSTF scheduling is a form of SJF scheduling; may cause starvation of some requests
- total head movement: 236 cylinders

SCAN Scheduling

- disk head move from one end to the other end
- A.k.a. elevator algorithm
- total head movement: 236 cylinders

C-SCAN Scheduling

- Disk head move in one direction only
- A variant of SCAN to provide more uniform wait time

C-LOOK Scheduling

version of C-SCAN

■ Disk head moves only to the last request location

Selecting Disk-Scheduling Algorithm

B SSTF

 \triangleright common and has a natural appeal, but not optimal

B SCAN

- \triangleright perform better for disks with heavy load
- **No** starvation problem
- C-SCAN
	- \triangleright More uniform wait time
- Performance is also influenced by the file-allocation method
	- **► Contiguous: less head movement**
	- \triangleright Indexed & linked: greater head movement

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Review Slides (I)

- 3 major components in disk-access time
	- \triangleright Seek
	- \triangleright Rotation
	- \triangleright Read
- Goal of disk-scheduling algorithm?
- Disk-scheduling algorithms
	- \triangleright FCFS
	- $>$ SSTF
	- \triangleright SCAN
	- \triangleright C-SCAN
	- \triangleright C-LOOK

Disk Management Formatting **Booting** Bad block Swap space

Disk Formatting

- Low-level formatting (or physical formatting): dividing a disk (magnetic recording material) into sectors that disk controller can read and write
	- \triangleright each sector = header + data area + trailer
		- header & trailer: sector # and ECC (error-correcting code)
		- ECC is calculated based on all bytes in data area
		- data area size: 512B, 1KB, 4KB
- OS does the next 2 steps to use the disk
	- \triangleright partition the disk into one or more groups of cylinders
	- \triangleright logical formatting (i.e. creation of a file system)

Boot Block

■ Bootstrap program

≻Initialize CPU, registers, device controllers, memory, and then starts OS

First **bootstrap code** stored in ROM

Complete bootstrap in the **boot block** of the boot disk (aka system disk)

Booting from a Disk in Windows 2000

- 1. Run bootstrap code in ROM
- 2. Read boot code in MBR(Master boot record)
- 3. Find boot partition from partition table
- 4. Read boot sector/block and continue booting

Bad Blocks

- Simple disks like IDE disks
	- Manually use format program to mark the corresponding FAT entry of the bad block
	- \triangleright Bad blocks are locked away from allocation
- Sophisticated disks like SCSI disks
	- \triangleright disk controllers maintains the list of bad blocks
	- \triangleright List is updated over the life of the disk
- **Sector sparing** (forwarding): remap bad block to a spare one
	- Could affect disk-scheduling performance
	- \triangleright A few spare sectors in each cylinder during formatting
- **Sector slipping:** ships sectors all down one spot

Swap-Space Management

- Swap-space: virtual memory use disk space (swap-space) as an extension of main mem
- UNIX: allows use of multiple swap spaces **Location**
	- \triangleright part of a normal file system (e.g. NT)
		- Less efficient
	- \triangleright separate disk partition (raw partition)
		- Size is fixed

\triangleright allows access to both types (e.g. Linux)

Swap Space Allocation

- 1st version: copy entire process between contiguous disk regions and memory
- 2nd version: copy pages to swap space
	- \triangleright Solaris 1:
		- **text segments** read from file system, thrown away when pageout
		- Only **anonymous memory** (stack, heap, etc) store in swap space
	- \triangleright Solaris 2:
		- swap-space allocation only when **pageout** rather than **virtual memory creation time**

Data Structures for Swapping (Linux)

RAID Structure

DRAM Price (1981 – 2008)

Magnetic Hard Disk Price (1981 – 2008)

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RAID Disks

RAID = **R**edundant **A**rrays of **I**nexpensive **D**isks

- provide **reliability** via **redundancy**
- improve **performance** via **parallelism**
- RAID is arranged into different levels
	- \triangleright Striping
	- Mirror (Replication)
	- **► Error-correcting code (ECC) & Parity bit**

RAID 0 & RAID 1

RAID 0: non-redundant **striping**

- Improve **performance** via **parallelism**
- \triangleright I/O bandwidth is proportional to the striping count
	- **Both read and write BW increase by N times (N is the number of disks)**
- RAID 1: **Mirrored** disks
	- Provide **reliability** via **redundancy**
		- **Read BW increases by N times**
		- **Write BW remains the same** RAID 0

Disk 0 Disk 1 Chapter12 Mass Storage System

Disk 0 Disk 1 Operating System Concepts – NTHU LSA Lab 28

RAID0 Example File1: 0011 File2: 110101

RAID 2: Hamming code

- E.g.: Hamming code(7,4)
	- \triangleright 4 data bits (on 4 disks) + 3 parity bits (on 3 disks)
	- \triangleright Each parity bit is linear code of 3 data bits
- *<u>ORecover from any single disk failure</u>*
	- Can detect up to two disks(i.e. bits) error
	- **► But can only "correct" one bit error**

Better space efficient than RAID1 (75% overhead)

Hamming code reference: http://en.wikipedia.org/wiki/Hamming_code

RAID 3 & 4: Parity Bit

- **Disk controller can detect whether a sector has been** read correctly
- \rightarrow a single parity bit is enough to correct error from a single disk failure
- **RAID 3**: Bit-level striping; **RAID 4**: Block-level striping
- Even better space efficiency (33% overhead)
- **© Cost to compute & store parity bit**
- RAID4 has higher I/O throughput, because controller does not need to reconstruct block from multiple disks

 $\mathbf{A}1$ **B1** $C1$ $D1$

 $Chapter 12$ $DiskO$ $Disk1$ $Disk2$ $Disk3$ 30

RAID 5: Distributed Parity

■ Spread data & parity across all disks

Prevent over use of a single disk (e.g. RAID 3,4)

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RAID 5: Distributed Parity

- Read BW increases by N times, because all four disks can serve a read request
- Write BW
	- Method1: (1)read out all unmodified (N-2) data bits. (2) re-compute parity bit. (3) write both modified bit and parity bit to disks.
	- \rightarrow write BW = N / ((N-2)+2) = 1 \rightarrow remains the same
	- \triangleright Method2: (1) only read the parity bit and modified bit. (2) re-compute parity bit by the difference. (3) write both modified bit and parity bit.

write BW = N $/(2+2)$ = N/4 times faster

RAID 6: P+Q Dual Parity Redundancy

- Like RAID 5, but stores extra redundant information to guard against **multiple disk failure**
- Use ECE code (i.e. Error Correction Code) instead of single parity bit
- Parity bits are also striped across disks

Chapter12 Mass Storage System Operating System Concepts – NTHU LSA Lab 34 *First level often control by a controller. Therefore, RAID 10 has better fault tolerance than RAID 01 when multiple disk fails http://www.thegeekstuff.com/2011/10/raid10-vs-raid01/

Review Slides (II)

- Swap space using FS? Raw partition?
- How to reduce swap space usage?
- RAID disks? Purpose?
- $RAD-0~6$?
- RAID 0+1, RAID 1+0

Reading Material & HW

■ Chapter 12

Problem Set

- > 12.1
- > 12.3
- > 12.8

Sector Sparing Example

- OS tries to read block 87
- controller finds out 87 is bad block, reports to OS
- next time system rebooted, controller replaces the bad block with a spare
- OS requests block 87 again, controller reads the spare block instead